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this book contains the most important formulas and more than 190 completely solved problems from kinetics and hydrodynamics it provides engineering students material to improve their skills and helps to gain experience in solving engineering problems particular emphasis is placed on finding the solution path and formulating the basic equations topics include kinematics of a point kinetics of a point mass dynamics of a system of point masses kinematics of rigid bodies kinetics of rigid bodies impact vibrations non inertial reference frames hydrodynamics

this volume documents on going research and theorising in the sub field of mathematics education devoted to the teaching and learning of mathematical modelling and applications mathematical modelling provides a way of conceiving and resolving problems in the life world of people whether these range from the everyday individual numeracy level to sophisticated new problems for society at large mathematical modelling and real world applications are considered as having potential for multi disciplinary work that involves knowledge from a variety of communities of practice such as those in different workplaces e g those of educators designers construction engineers museum curators and in different fields of academic endeavour e g history archaeology mathematics economics from an educational perspective researching the development of competency in real world modelling involves research situated in crossing the boundaries between being a student engaged in modelling or mathematical application to real word tasks in the classroom being a teacher of mathematical modelling in or outside the classroom or bridging both and being a modeller of the world outside the classroom this is the focus of many of the authors of the chapters in this book all authors of

this volume are members of the international community of teachers of mathematical modelling ictma the peak research body into researching the teaching and learning of mathematical modelling at all levels of education from the early years to tertiary education as well as in the workplace

suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course it offers the comprehensive solved problem reference in the subject it also provides the student with the problem solving drill

this book constitutes the post conference proceedings of the 2nd international conference on modern problems of robotics mpor 2020 held in moscow russia in march 2020 the 16 revised full papers were carefully reviewed and selected from 21 submissions the volume includes the following topical sections collaborative robotic systems robotic systems design and simulation and robots control the papers are devoted to the most interesting today s investigations in robotics such as the problems of the human robot interaction the problems of robot design and simulation and the problems of robot and robotic complexes control

this book highlights an analytical solution for the dynamics of axially rotating objects it also presents the theory of gyroscopic effects explaining their physics and using mathematical models of euler s form for the motion of movable spinning objects to demonstrate these effects the major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and coriolis forces as well as the change in the angular momentum the interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the principle of mechanical energy conservation these kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc lastly the mathematical models for the gyroscopic effects are validated by practical tests the 2nd edition became necessary due to new development and corrections of mathematical expressions it contains new chapters about the tippe top inversion and inversion of the spinning object in an orbital flight and the boomerang aerodynamics

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