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market desc mechanical and civil engineers special features contains the strongest coverage on how to draw free body diagrams of any book on the market theory sections have been extensively rewritten new application areas especially biomechanics and new computer extension problems that introduce uses of computer tools for design and what if analysis about the book concise and authoritative this book sets the standard for excellence in basic mechanics texts the major emphasis is on basic principles and problem formulation strong effort has been made to show both the cohesiveness of the relatively few fundamental ideas and the great variety of problems

that these ideas solve all of the problems deal with principles and procedures inherent in the design and analysis of engineering structures and mechanical systems with many of the problems referring explicitly to design considerations

this volume offers a concise presentation of engineering mechanics theory and application the material is reinforced with numerous examples to illustrate principles and imaginative problems of varying degrees of difficulty

presents a step by step approach to modeling analysis and control covering fundamental theory practical implementation and advanced strategies aimed at senior undergraduates and first year graduates it includes real world examples solved problems and exercises and is supported online by a solutions manual matlab code and simulink files

the revision of this classic text continues to provide the same high quality material seen in previous editions in addition the fifth edition provides extensively rewritten updated prose for content clarity superb new problems in new application areas outstanding instruction on drawing free body diagrams and new electronic supplements to assist learning and instruction if you think you have seen meriam kraige before take another look it s not what you remember it to be it s better based problem solving egrade gives students opportunity to practice solving problems with immediate feedback computational mechanics booklets offer flexibility in introducing matlab mathcad and or maple into your mechanics classroom electronic figures from the text allow you to enhance your lectures by pulling material from the text into your powerpoint or other lecture formats 100 additional electronic transparencies offer problem statements and fully worked solutions for use in lecture or as outside study tools for students

this book is all about mechanisms and machines one of the most important core subjects of mechanical engineering there are many ways a mechanism can be configured and there are many mechanisms in a machine creating a tremendous opportunity to build better machines of our choice to do so however one needs to understand the common thread present in the thousands of configurations and to break them down into a set of rules this book does exactly that using the same set of rules consistently to explain the design of any mechanism or machine pedagogical tools and approaches have been utilized to make it easier and more interesting for the student extensive illustrations simple explanations and exercise problems with useful hints have been included the systematic use of a vector based approach makes learning easier and helps extend the knowledge acquired in this book to applications in robotics

a thorough study of the oscillatory and transient motion of mechanical and structural systems engineering vibrations second edition presents vibrations from a unified point of view and builds on the first edition with additional chapters and sections that contain more advanced graduate level topics using numerous examples and case studies the author reviews basic principles incorporates advanced abstract concepts from first principles and weaves together physical

interpretation and fundamental principles with applied problem solving this revised version combines the physical and mathematical facets of vibration and emphasizes the connecting ideas concepts and techniques

this book is a comprehensive treatment of engineering undergraduate differential equations as well as linear vibrations and feedback control while this material has traditionally been separated into different courses in undergraduate engineering curricula this text provides a streamlined and efficient treatment of material normally covered in three courses ultimately engineering students study mathematics in order to be able to solve problems within the engineering realm engineering differential equations theory and applications guides students to approach the mathematical theory with much greater interest and enthusiasm by teaching the theory together with applications additionally it includes an abundance of detailed examples appendices include numerous c and fortran example programs this book is intended for engineering undergraduate students particularly aerospace and mechanical engineers and students in other disciplines concerned with mechanical systems analysis and control prerequisites include basic and advanced calculus with an introduction to linear algebra

parallel structures are more effective than serial ones for industrial automation applications that require high precision and stiffness or a high load capacity relative to robot weight although many industrial applications have adopted parallel structures for their design few textbooks introduce the analysis of such robots in terms of dynamics and control filling this gap parallel robots mechanics and control presents a systematic approach to analyze the kinematics dynamics and control of parallel robots it brings together analysis and design tools for engineers and researchers who want to design and implement parallel structures in industry covers kinematics dynamics and control in one volume the book begins with the representation of motion of robots and the kinematic analysis of parallel manipulators moving beyond static positioning it then examines a systematic approach to performing jacobian analysis a special feature of the book is its detailed coverage of the dynamics and control of parallel manipulators the text examines dynamic analysis using the newton euler method the principle of virtual work and the lagrange formulations finally the book elaborates on the control of parallel robots considering both motion and force control it introduces various model free and model based controllers and develops robust and adaptive control schemes it also addresses redundancy resolution schemes in detail analysis and design tools to help you create parallel robots in each chapter the author revisits the same case studies to show how the techniques may be applied the case studies include a planar cable driven parallel robot part of a promising new generation of parallel structures that will allow for larger workspaces the matlab code used for analysis and simulation is available online combining the analysis of kinematics and dynamics with methods of designing controllers this text offers a holistic introduction for anyone interested in designing and implementing parallel robots

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