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known for its accuracy clarity and dependability meriam kraige and bolton s engineering mechanics statics 9th edition has provided a solid foundation of mechanics principles for more than 60 years this text continues to help students develop their problem solving skills with an extensive variety of engaging problems related to engineering design in addition to new homework problems the text includes a number of helpful sample problems to help students build necessary visualization and problem solving skills the text strongly emphasizes drawing free body diagrams one of the most important skills needed to solve mechanics problems

this book introduces machine dynamics an essential competency important for many applications such as designing robots for manufacturing materials handling or the landing gear of an airplane analyzing the motion of a piston in an internal combustion engine or a compressor and designing a mars rover wherever a machine is used for force or power transmission or a mechanism creates a desired motion the methods studied in this book provide the fundamental knowledge needed for optimal design specific sections are provided on different types of mechanisms and conditions that should be met for obtaining a desired performance including kinematic analysis of mechanisms direct differentiation relative motion kinematic coefficients instantaneous centers the newton raphson method for solving complex nonlinear position analysis problems is discussed and the determination of dead and limit positions in mechanisms is presented the relation between the angular velocity ratio theorem and the fundamental law of gearing is shown to provide a bridge between the concept of instantaneous centers and analyzing gears gears and gear trains are covered in detail and calculation of gear ratios in fixed axis and planetary gear trains using the rolling contact equations is illustrated finally power and force transmission in machines is covered static and dynamic cases are analyzed and the author shows how the static solutions can provide approximations for the dynamic problems where inertia effects are not significant low inertia and low accelerations application of matrix algebra for solving the system of equations of equilibrium in statics or equations of motion in dynamics is also illustrated because of the importance of balancing in any application involving rotating machinery static and dynamic balancing are analyzed the book concludes with a brief coverage of three dimensional dynamics including euler s equations and gyroscopic effect aimed at engineering students interested in machine dynamics across a range of disciplines the book is also ideal as a reference for practicing engineers with a good understanding of statics dynamics and matrix algebra

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