

Gibbs Is Another Common Model Of Reflection That Is Afpp

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this festschrift volume published in honor of manfred nagl on the occasion of his 65th birthday contains 30 refereed contributions that cover graph transformations software architectures and reengineering embedded systems engineering and more

design reuse is not just a topic of research but a real industrial necessity in the microelectronic domain and thus driving the competitiveness of relevant areas like for example telecommunication or automotive most companies have already dedicated a department or a central unit that transfer design reuse into reality all main eda conferences include a track to the topic and even specific conferences have been established in this area both in the usa and in europe virtual components design and reuse presents a selection of articles giving a mature and consolidated perspective to design reuse from different points of view the authors stem from all relevant areas research and academia ip providers eda vendors and industry some classical topics in design reuse like specification and generation of components ip retrieval and cataloguing or interface customisation are revisited and discussed in depth moreover new hot topics are presented among them ip quality platform based reuse software ip ip security business models for design reuse and major initiatives like the medea eda roadmap

in a model based development of software systems different views on a system are elaborated using appropriate modeling languages and techniques because of the unavoidable heterogeneity of the viewpoint models a semantic integration is required to establish the correspondences of the models and allow checking of their relative consistency the integration approach introduced in this book is based on a common semantic domain of abstract systems their composition and development its applicability is shown through semantic interpretations and compositional comparisons of different specification approaches these range from formal specification techniques like process calculi petri nets and rule based formalisms to semiformal software modeling languages like those in the uml family

geographic information science giscience is an emerging field that combines aspects of many different disciplines spatial literacy is rapidly becoming recognized as a new essential pier of basic education alongside grammatical logical and mathematical literacy by incorporating location as an essential but often overlooked characteristic of what we seek to understand in the natural and built environment geographic information science giscience and systems gisystems provide the conceptual foundation and tools to explore this new frontier the encyclopedia of geographic information science covers the essence of this exciting new and expanding field in an easily understood but richly detailed style in addition to contributions from some of the best recognized scholars in giscience this volume contains contributions from experts in gis supporting disciplines who explore how their disciplinary perspectives are expanded within the context of giscienceâ what changes when consideration of location is added what complexities in analytical procedures are added when we consider objects in 2 3 or even 4 dimensions what can we gain by visualizing our analytical results on a map or 3d display key features brings together giscience literature that is spread widely across the academic spectrum offers details about the key foundations of giscience no matter what their disciplinary origins elucidates vocabulary that is an amalgam of all of these fields key themes conceptual foundations cartography and visualization design aspects data manipulation data modeling geocomputation geospatial data societal issues spatial analysis organizational and institutional aspects the encyclopedia of geographic information science is an important resource for academic and corporate libraries

semantic technologies are experimenting an increasing popularity in the context of different domains and applications the understanding of any class of system can be significantly changed under the assumption any system is part of a global ecosystem known as semantic the semantic would be an evolving extension of current model normally referred as syntactic that introduces a semantic layer in which semantics or meaning of information are formally defined so semantics should integrate web centric standard information infrastructures improving several aspects of interaction among heterogeneous systems this is because common interoperability models are progressively becoming obsolete if compared with the intrinsic complexity and always more distributed focus that feature modern systems for example the basic interoperability model that assumes the interchange of messages among systems without any interpretation is simple but effective only in the context of close

environments also more advanced models such as the functional interoperability model that integrates basic interoperability model with the ability of interpreting data context under the assumption of a shared schema for data fields accessing appears not able to provide a full sustainable technologic support for open systems the semantic interoperability model would improve common interoperability models introducing the interpretation of means of data semantic interoperability is a concretely applicable interaction model under the assumption of adopting rich data models commonly called ontology composed of concepts within a domain and the relationships among those concepts in practice semantic technologies are partially inverting the common view at actor intelligence intelligence is not implemented only by actors but it is implicitly resident in the knowledge model in other words schemas contain information and the code to interpretate it

this thesis proposes a method that plans trajectories for autonomous agents to enable them to fulfil different tasks while ensuring the collision free movement the agents are locally controlled and connected over an unreliable communication network that may induce packet losses and transmission delays further sensors e.g. for a distance measurement are not used and communication should only be invoked if it is necessary to avoid a collision the basic problem occurs for two agents the first agent can change its trajectory at any time without regard to the second agent which has to ensure the collision avoidance to this aim it adapts its trajectory based only on local data and communicated information about the current and future movement of the first agent a control unit for the second agent is introduced that has to execute four tasks to ensure the control aims 1 estimation of the current network properties 2 prediction of the movement of the stand on agent 3 invocation of communication whenever the local data becomes too uncertain 4 planning of collision avoiding trajectories the main result of the thesis is a novel control method for mobile agents that solves the four tasks leading to a proven collision avoidance the method consists of a delay estimator a prediction unit an event generator and a trajectory planning unit the method can be used for different types of agents e.g. uavs or cars with only slight modifications the proposed method is tested and evaluated through simulations and experiments with both two quadrotors and two nonholonomic robots

this volume constitutes the refereed proceedings of the 14th international conference on

hybrid artificial intelligent systems hais 2019 held in león spain in september 2019 the 64 full papers published in this volume were carefully reviewed and selected from 134 submissions they are organized in the following topical sections data mining knowledge discovery and big data bio inspired models and evolutionary computation learning algorithms visual analysis and advanced data processing techniques data mining applications and hybrid intelligent applications

the standard theory of decision making under uncertainty advises the decision maker to form a statistical model linking outcomes to decisions and then to choose the optimal distribution of outcomes this assumes that the decision maker trusts the model completely but what should a decision maker do if the model cannot be trusted lars hansen and thomas sargent two leading macroeconomists push the field forward as they set about answering this question they adapt robust control techniques and apply them to economics by using this theory to let decision makers acknowledge misspecification in economic modeling the authors develop applications to a variety of problems in dynamic macroeconomics technical rigorous and self contained this book will be useful for macroeconomists who seek to improve the robustness of decision making processes

managing it in construction managing construction for tomorrow presents new developments in managing it strategies model based management tools including building information modeling information and knowledge management communication and collaboration data acquisition and storage visualization and simulation architectural design and

veterinary anesthesia and analgesia the fifth edition of lumb and jones is a reorganized and updated edition of the gold standard reference for anesthesia and pain management in veterinary patients provides a thoroughly updated edition of this comprehensive reference on veterinary anesthesia and analgesia combining state of the art scientific knowledge and clinically relevant information covers immobilization sedation anesthesia and analgesia of companion wild zoo and laboratory animals takes a body systems approach for easier reference to information about anesthetizing patients with existing conditions adds 10 completely new chapters with in depth discussions of perioperative heat balance coagulation disorders pacemaker implantation cardiac output measurement cardiopulmonary bypass shelter anesthesia and pain management anesthetic risk assessment principles of anesthetic pharmacology and more now printed

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an overview of chemical fate and transport modeling in the vadose zone chemical processes parameter estimation and variability in the vadose zone mathematical derivation of chemical transport equations

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