

Flying Fish Sensor

Proceedings of the Multimedia University Engineering Conference (MECON 2022)The Life Cycle of the Centric Diatom Thalassiosira WeissflogiiEmerging Trends in Computing and Expert TechnologyTunnelling into a Sustainable Future 2 Methods and TechnologiesCongress on Research, Development and Innovation in Renewable EnergiesOceans '96 MTS/IEEEThe Ascension FactorAn Entropic Framework for AUV Sensor ModellingOceans' 88 ProceedingsOceans '88 22222222Marine Technology Society JournalUnderwater TechnologyThe Flying Fish, an Untethered Oceanographic Sensor Platform with Acoustic Homing CapabilityA DIY Smart Home Guide: Tools for Automating Your Home Monitoring and Security Using Arduino, ESP8266, and AndroidProceedings of the ... International Symposium on Underwater TechnologyThe Flying FishConference ProceedingsAviation Week & Space TechnologyMan's Extension Into the Sea Mohamad Yusoff bin Alias Elisabeth Virginia Armbrust D. Jude Hemanth Fredrik Johansson Mayken Espinoza-Andaluz Frank Herbert Hanumant Singh Oceanic Engineering Society (U.S.) Robert Chin Joshua King Hoyt

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this is an open access book the multimedia university engineering conference 2022 mecon 2022 aims to bring together related research scholars educators practitioners policy makers enthusiasts fellow students and industries to share and exchange their research experiences and results on all aspects of engineering technologies from various perspectives disciplines and fields it also offers an interdisciplinary platform for all stakeholders to present and discuss the most latest trends innovations and concerns as well as practical challenges encountered and solutions adopted in the realm of engineering technologies this conference is being co organised by the faculty of engineering foe and faculty of engineering and technology fet multimedia university mecon 2022 carries the theme sustainable engineering for a sustainable future

the goal of this research was to understand what factors determine whether a diatom cell can exit the mitotic cell cycle to undergo gametogenesis and subsequent auxospore formation using flow cytometry i found that the centric diatom thalassiosira weissflogii could be induced to undergo spermatogenesis by exposing cells maintained in continuous light to either dim light or darkness the use of populations representing distinct cell cycle distributions indicated that cells in early g1 could be triggered to form male gametes whereas cells further along in their cell cycle were unresponsive to these same cues the size distributions of numerous isolates maintained under identical conditions were examined over time to determine the relation between cell size and the ability to undergo sexual reproduction each isolate underwent periodic increases and decreases in mean cell size as expected for populations alternating between asexual and sexual reproduction however the timing of the onset of sexual reproduction the rate of increase in mean cell size and the size of the post auxospores created during a sexual event varied among isolates and within a given isolate over time this variable behavior was hypothesized to occur

because the genetic composition of diatom populations varies over time keywords medicine

this book presents high quality research papers that demonstrate how emerging technologies in the field of intelligent systems can be used to effectively meet global needs the respective papers highlight a wealth of innovations and experimental results while also addressing proven it governance standards and practices and new designs and tools that facilitate rapid information flows to the user the book is divided into five major sections namely advances in high performance computing advances in machine and deep learning advances in networking and communication advances in circuits and systems in computing and advances in control and soft computing

tunnelling into a sustainable future methods and technologies contains the contributions presented at the ita aites world tunnel congress 2025 stockholm sweden 9 15 may 2025 the contributions cover a wide range of topics in the fields of tunnelling and underground engineering including 1 innovating tunneling 2 safety underground 3 use of underground space 4 investigations and ground characterisation 5 planning and design of underground space 6 conventional tunnelling 7 mechanised tunnelling 8 complex geometries including shafts and ramps 9 grouting and groundwater control 10 instrumentation and monitoring 11 operation inspection and maintenance 12 contractual aspects financing and risk management 13 impact from climate change tunnelling into a sustainable future methods and technologies will serve as a valuable reference to all concerned with tunnelling and underground engineering including students researchers and engineers

renewable energy research development and innovation selected papers from cidier 2024 presents international collaborations that foster ideas and dialogue around solutions to climate change through research and development that leads to clean energy innovation via renewable energies the book includes chapters based on selected papers from the 2024 congress on research development and innovation in renewable energies cidier 2024 that cover theoretical and applied research that will strengthen the implementation of renewable energy projects between universities research centers and private companies in latin america presents leading edge research on advancing renewable energy promotes research and innovation with a focus on latin america covers biomass hydraulic hydrogen tidal solar and wind energy

this final book in the destination void collaboration between frank herbert and bill ransom set twenty five years after the previous book the lazarus effect concludes the story of the planet pandora a stunning work from the acclaimed author of dune the series which inspired the 2021 denis villeneuve epic film adaptation dune starring oscar isaac timoth e chalamet zendaya and josh brolin

this thesis examines the general task of active sensing by defining a measure of efficiency for sensing in a particular environment we focus on fine scale acoustic mapping from an autonomous underwater vehicle auv the constraints on imaging underwater vehicle power vehicle hydrodynamics computational and telemetry requirements and typical navigational and attitudinal uncertainties along with the underlying physics of the acoustic sensing modality are considered in defining an entropic measure of sensor efficiency 675 khz pencil beam sonar data acquired using the jason remotely operated vehicle in a challenging shallow water environment and 200 khz echo sounder data acquired using the abe a uv are used to demonstrate the utility of the en tropic framework we show the utility of an entropic framework for the following i optimizing the speed of the auv for maximizing the information gathered with a particular sensor ii the rate of convergence and the stability of our mapping efforts in the face of typical uncertainties in navigation and attitude iii as a methodology for actual sensor deployment and use on a real vehicle and iv in tasks such as post mission analysis for applications such as change detection and path planning for subsequent missions

a primary goal of ieee oes is to take its symposiums around the world where emerging technology and applications can be synthesized into solutions for the future key issues for the global underwater environment provides a thematic umbrella under which the problems and potential long term solutions

which concern not only the pacific rim countries but the world in general are discussed

this research was conducted under nsf contract number oce 8310168

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