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this book presents essential knowledge of car vehicle dynamics and control theory with ni labview software product application resulting in a practical yet highly technical guide for designing advanced vehicle dynamics and vehicle system controllers presenting a clear overview of fundamental vehicle dynamics and vehicle system mathematical models the book covers linear and non linear design of model based controls such as wheel slip control vehicle speed control path following control vehicle stability and rollover control stabilization of vehicle trailer system specific applications to autonomous vehicles are described among the methods it details the practical applications of kalman bucy filtering and the observer design for sensor signal estimation alongside lateral vehicle dynamics and vehicle rollover dynamics the book also discusses high level controllers alongside a clear explanation of basic control principles for regenerative braking in both electric and hybrid vehicles and wheel torque vectoring systems concrete labview simulation examples of how the models and controls are used in representative applications along with software algorithms and labview block diagrams are illustrated it will be of interest to engineering students automotive engineering students and automotive engineers and researchers

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