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the purpose of this research topic is to reflect and discuss links between neuroscience psychology computer science and robotics with regards to the topic of cross modal learning which has in recent years emerged as a new area of interdisciplinary research the term cross

modal learning refers to the synergistic synthesis of information from multiple sensory modalities such that the learning that occurs within any individual sensory modality can be enhanced with information from one or more other modalities cross modal learning is a crucial component of adaptive behavior in a continuously changing world and examples are ubiquitous such as learning to grasp and manipulate objects learning to walk learning to read and write learning to understand language and its referents etc in all these examples visual auditory somatosensory or other modalities have to be integrated and learning must be cross modal in fact the broad range of acquired human skills are cross modal and many of the most advanced human capabilities such as those involved in social cognition require learning from the richest combinations of cross modal information in contrast even the very best systems in artificial intelligence ai and robotics have taken only tiny steps in this direction building a system that composes a global perspective from multiple distinct sources types of data and sensory modalities is a grand challenge of ai yet it is specific enough that it can be studied quite rigorously and in such detail that the prospect for deep insights into these mechanisms is quite plausible in the near term cross modal learning is a broad interdisciplinary topic that has not yet coalesced into a single unified field instead there are many separate fields each tackling the concerns of cross modal learning from its own perspective with currently little overlap we anticipate an accelerating trend towards integration of these areas and we intend to contribute to that integration by focusing on cross modal learning the proposed research topic can bring together recent progress in artificial intelligence robotics psychology and neuroscience

the area of intelligent control is a fusion of a number of research areas in engineering computer science and mathematics which has evolved from conventional control to enhance the existing nonlinear optimal adaptive and stochastic control methods intelligent control techniques are currently being utilized for closed loop feedback control in space based applications manufacturing systems robotic systems avionic systems among others to improve system performance reliability and efficiency overall the primary objective of intelligent control is to enhance the performance of the system to the extent that it achieves some level of autonomous control

contains five papers and an invited talk from a may 1999 colloquium acknowledging the

contributions of dr harlan mills to the theory and practice of software engineering and widespread applications to the emerging challenges in software engineering subjects include coupling and strength developin

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